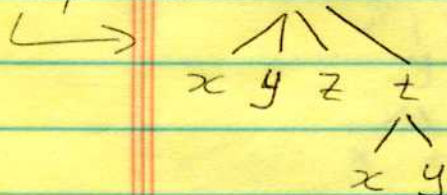


14.9.2)  $w = x^2 + y - z + \sin t$  and  $x + y = t$ .

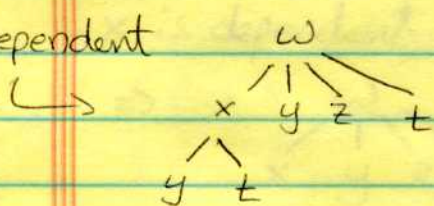
a)  $\left(\frac{\partial w}{\partial y}\right)_{x,z} = \frac{\partial w}{\partial y} + \frac{\partial w}{\partial t} \frac{dt}{dy}$

$t$  dependent  $w$   $= 1 + \cos t$

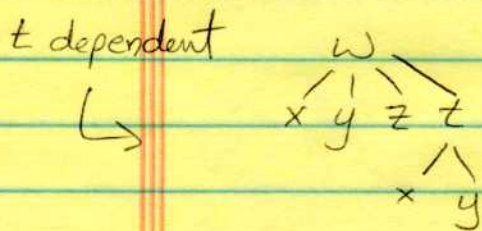


b)  $\left(\frac{\partial w}{\partial y}\right)_{z,t} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial y} + \frac{\partial w}{\partial y}$

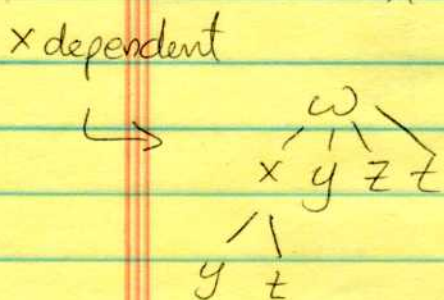
$x$  dependent  $= 2x(-1) + 1 = 1 - 2x$



c)  $\left(\frac{\partial w}{\partial z}\right)_{x,y} = \frac{\partial w}{\partial z} + \cancel{\frac{\partial w}{\partial t} \frac{dt}{dz}} = -1$



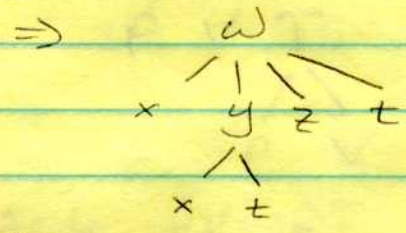
d)  $\left(\frac{\partial w}{\partial z}\right)_{y,t} = \frac{\partial w}{\partial z} = -1$



14.9.2)  
continued

$$e) \left( \frac{\partial w}{\partial t} \right)_{x,z} = \frac{\partial w}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial w}{\partial t}$$
$$= 1(\cancel{1}) + \text{cost} = 1 + \text{cost}$$

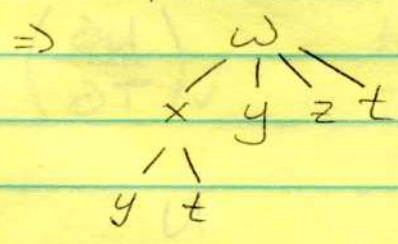
y is dependent



$$f) \left( \frac{\partial w}{\partial t} \right)_{y,z} = \frac{\partial w}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial w}{\partial t}$$
$$= 2x(1) + \text{cost}$$

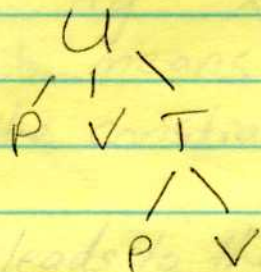
x is dependent

$$= 2x + \text{cost}$$



14.9.3)

$\left(\frac{\partial u}{\partial P}\right)_V$  tells us  $P, V$  are independent variables.  
Therefore,  $T$  is dependent.



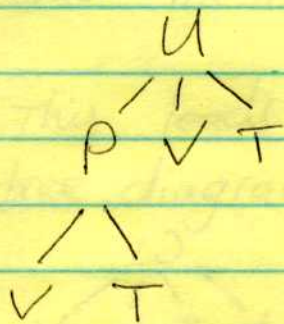
$$\begin{aligned}\left(\frac{\partial u}{\partial P}\right)_V &= \frac{\partial u}{\partial P} + \frac{\partial u}{\partial T} \frac{\partial T}{\partial P} \\ &= \frac{\partial f}{\partial P} + \frac{\partial f}{\partial T} \left(\frac{V}{nR}\right)\end{aligned}$$

Aside:  $PV = nRT$

$$T = \frac{PV}{nR}$$

$$\frac{\partial T}{\partial P} = \frac{V}{nR}$$

$\left(\frac{\partial u}{\partial T}\right)_V$  tells us  $T, V$  are independent variables.  
Therefore,  $P$  is dependent.



$$\begin{aligned}\left(\frac{\partial u}{\partial T}\right)_V &= \frac{\partial u}{\partial P} \frac{\partial P}{\partial T} + \frac{\partial u}{\partial T} \\ &= \frac{\partial f}{\partial P} \left(\frac{nR}{V}\right) + \frac{\partial f}{\partial T}\end{aligned}$$

Aside:  $PV = nRT$

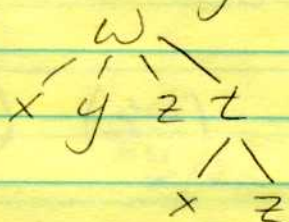
$$P = \frac{nRT}{V}$$

$$\frac{\partial P}{\partial T} = \frac{nR}{V}$$

14.9.8)  $w = x^2 - y^2 + 4z + t$  AND  $x + 2z + t = 25$ .

Let's try  $x, y, z$  as the independent variables, which means  $t$  is dependent (only on  $x, z$ , as the constraint is  $x + 2z + t = 25$ ).

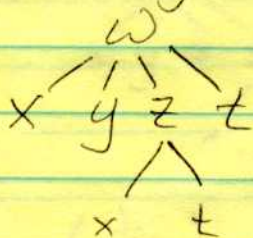
This leads to the tree diagram:



$$\begin{aligned} \left(\frac{\partial w}{\partial x}\right)_{y,z} &= \frac{\partial w}{\partial x} + \frac{\partial w}{\partial t} \frac{\partial t}{\partial x} \\ &= 2x + (1)(-1) \\ &= 2x - 1. \end{aligned}$$

Now let's try  $x, y, t$  as the independent variables, which means  $z$  is the dependent variable.

This leads to the tree diagram



$$\begin{aligned} \left(\frac{\partial w}{\partial x}\right)_{y,t} &= \frac{\partial w}{\partial x} + \frac{\partial w}{\partial z} \frac{\partial z}{\partial x} \\ &= 2x + (4)\left(-\frac{1}{2}\right) \\ &= 2x - 2. \end{aligned}$$