

## Questions

- (30) 1. In many physical problems the nonhomogeneous term may be specified by different formulas in different time periods. As an example, determine the solution of

$$y'' + y = \begin{cases} t & 0 \leq t \leq \pi \\ \pi e^{\pi-t} & t > \pi \end{cases}$$

satisfying the initial conditions  $y(0) = 0$  and  $y'(0) = 1$ . Assume that  $y$  and  $y'$  are continuous at  $t = \pi$ .

Plot the nonhomogeneous term and the solution as a function of time.

*Hint:* First solve the IVP for  $t \leq \pi$ ; then solve for  $t > \pi$ , determining the constants in the latter solution from the continuity and differentiability conditions at  $t = \pi$ .

To get the sketches asked for, use *Mathematica* and the intrinsic command **Piecewise**.

For example, to define the function

$$g(t) = \begin{cases} \sin(t + \pi/2) & t < 0 \\ t^2 + 1 & t \geq 0 \end{cases}$$

use `g[t_]=Piecewise[{{Sin[t+Pi/2],t<0},{t^2+1,t>=0}}`

*This problem gives you practice with the undetermined coefficients technique.*

- (30) 2. A *hardening spring* is a spring that does not satisfy Hooke's law, but instead the restoring force satisfies  $F_s = -(ku + \epsilon u^3)$  where  $\epsilon > 0$  is small (if  $\epsilon < 0$  it is called a softening spring). The effect of a hardening spring is that the restoring force is stronger for larger displacements than for a spring that satisfies Hooke's law.

The differential equation this spring satisfies is  $mu'' + \gamma u' + ku + \epsilon u^3 = F(t)$ .

Since this is nonlinear, our techniques of solution will not work. Analytic solutions are typically based around a perturbation method which exploits the fact that  $\epsilon$  is small. If you want to see more about the perturbation techniques, you can check out the following article:

<http://www.ewp.rpi.edu/hartford/ernesto/F2011/EP/MaterialsforStudents/Royle/Kimiaefar2009.PDF>

We will instead investigate using numerical solutions. Consider the IVP:

$$u'' + \frac{1}{5}u' + u + \frac{1}{5}u^3 = \cos(\omega t), \quad u(0) = 0, \quad u'(0) = 0.$$

- (a) Using *Mathematica's* command `NDSolve`, generate plots of the solution for several values of  $\omega$  between  $1/2$  and  $2$  and estimate the amplitude  $R$  of the steady-state response in each case (you can do this visually from a graph for a variety of  $\omega$ ).
- (b) Using the data from part (a), plot the graph of  $R$  versus  $\omega$ . For what frequency is the amplitude the greatest?
- (c) Compare the results in *a* and *b* with the results for the linear spring ( $\epsilon = 0$ , see Figure 3.8.2 in the text and read page 209 to create the graph like Fig 3.8.2 for this particular case).

*This problem gives you practice with Mathematica's numerical solver. We will develop a way later in the semester to solve problems like this one using a modification of Taylor's Method of Order  $n$ .*

- (20) 3. Find the real valued general solution to  $y^{(6)} + y = 0$ . Use the ideas from the roots of unity discussion to help you factor the characteristic equation (I want to see the details of this computation, including a sketch of the roots in the complex plane).

*This problem shows you one example of how roots of polynomials are related to differential equations.*

- (20) 4. Consider the initial value problem:  $4y^{(3)} + 4y^{(2)} + y^{(1)} + \beta y = 0$ ,  $y(0) = 0, y'(0) = 1, y''(0) = 3$ .

Solve and plot the IVP for  $\beta = \frac{2}{27}, \frac{2}{27} - \frac{1}{40}, \frac{2}{27} + \frac{1}{40}$ . What is special about the characteristic equation near  $\beta = \frac{2}{27}$ ?

You may use *Mathematica's* `DSolve` command on this problem.

*This problem shows the sensitivity of the solution to the value of  $\beta$  when  $\beta \sim \frac{2}{27}$ . This differential equation is also sensitive for  $\beta \sim 0$ .*