

**Theorem 1 Existence and Uniqueness Theorem (Theorem 3.2.1)** Consider the initial value problem

$$y'' + p(t)y' + q(t)y = g(t), \quad y(t_0) = y_0, \quad y'(t_0) = y'_0$$

where  $p, q$  and  $g$  are continuous on an open interval  $I$ . Then there exists exactly one solution  $y = \phi(t)$  of this problem, and the solution exists throughout the interval  $I$ .

**Theorem 2 Principle of Superposition (Theorem 3.2.2)** If  $y_1$  and  $y_2$  are two solutions of the differential equation

$$L[y] = y'' + p(t)y' + q(t)y = 0,$$

then the linear combination  $y(t) = c_1y_1 + c_2y_2$  is also a solution for any values of the constants  $c_1$  and  $c_2$ .

**Theorem 3 (Theorem 3.2.3)** Suppose that  $y_1$  and  $y_2$  are two solutions of

$$L[y] = y'' + p(t)y' + q(t)y = 0,$$

and that the Wronskian

$$W = y_1y'_2 - y'_1y_2,$$

is not zero at the point  $t_0$  where the initial conditions  $y(t_0) = y_0$ ,  $y'(t_0) = y'_0$  are assigned. Then there is a choice of constant  $c_1$  and  $c_2$  for which  $y = c_1y_1(t) + c_2y_2(t)$  satisfies the associated IVP.

**Theorem 4 (Theorem 3.2.4)** If  $y_1$  and  $y_2$  are two solutions of the DE:

$$L[y] = y'' + p(t)y' + q(t)y = 0,$$

and if there is a point  $t_0$  where the Wronskian of  $y_1$  and  $y_2$  is nonzero, then the family of solutions

$$y(t) = c_1y_1(t) + c_2y_2(t)$$

with arbitrary coefficients  $c_1$  and  $c_2$  includes every solution of the DE.

**Theorem 5 (Theorem 3.2.5)** Consider the DE

$$L[y] = y'' + p(t)y' + q(t)y = 0,$$

whose coefficients  $p, q$  are continuous on some open interval  $I$ . Choose some point  $t_0$  in  $I$ . Let  $y_1$  be the solution of the DE that also satisfies the initial conditions:

$$y(t_0) = 1, \quad y'(t_0) = 0,$$

and let  $y_2$  be the solution of the DE that also satisfies the initial conditions:

$$y(t_0) = 0, \quad y'(t_0) = 1.$$

Then  $y_1$  and  $y_2$  form a fundamental set of solutions for the DE.

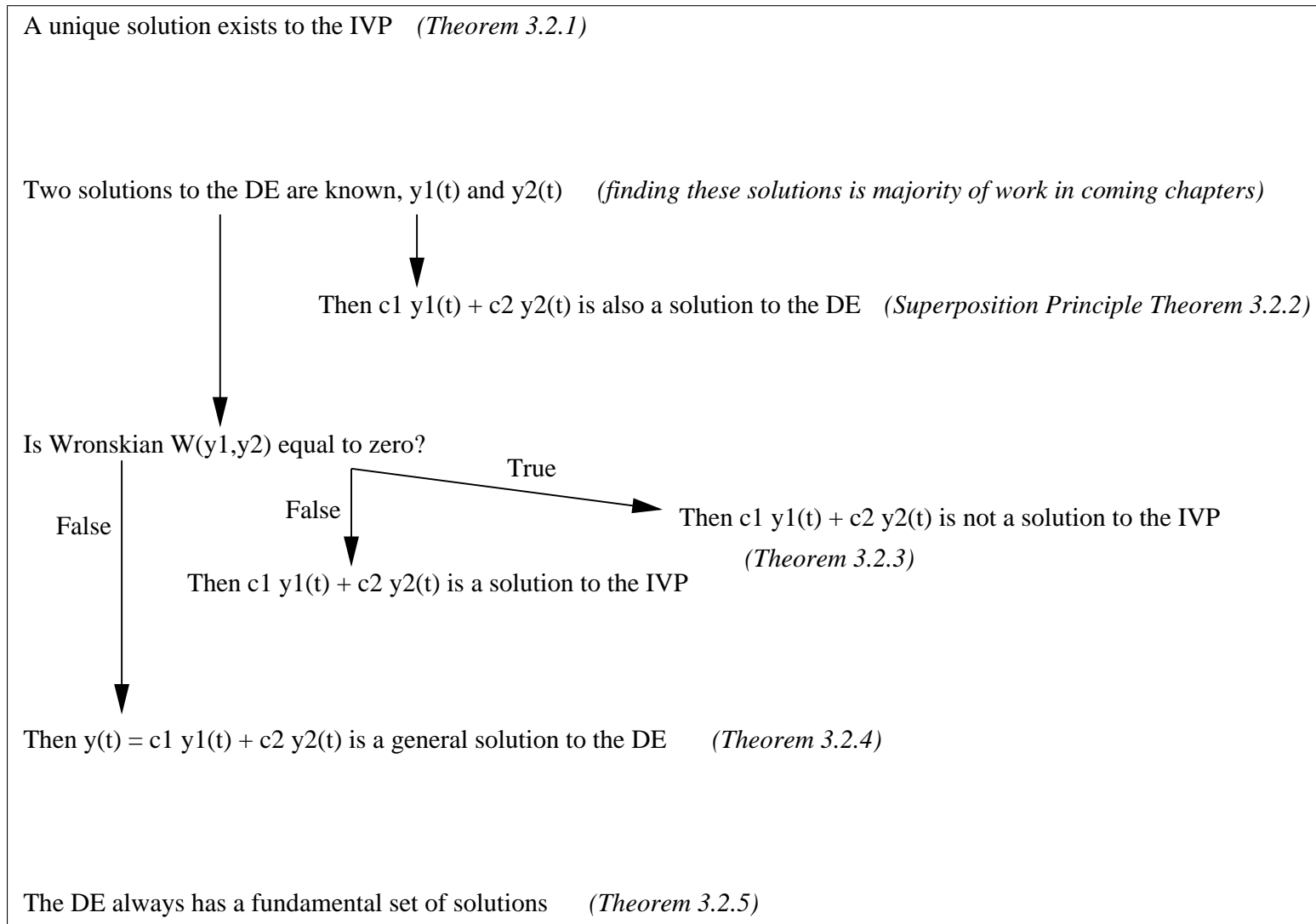
Here is a concept map of how the theorems relate. In what follows we have

$$\text{DE: } y''(t) + p(t)y'(t) + q(t)y(t) = 0,$$

$$\text{IVP: } y''(t) + p(t)y'(t) + q(t)y(t) = 0, \quad y(t_0) = y_0, \quad y'(t_0) = y'_0.$$

where  $p$ ,  $q$  and  $g$  are continuous in an interval  $I$ .

Note that Theorem 3.2.1 also applies to nonhomogeneous linear differential equations.



**Theorem 6 Abel's Theorem (Theorem 3.2.6)** If  $y_1$  and  $y_2$  are solutions of the differential equation

$$L[y](t) = y'' + p(t)y' + q(t)y = 0,$$

where  $p$  and  $q$  are continuous on an open interval  $I$ , then the Wronskian  $W(y_1, y_2)(t)$  is given by:

$$W(y_1, y_2)(t) = c \exp \left[ - \int p(t) dt \right],$$

where  $c$  is a certain constant that depends on  $y_1, y_2$ , but not on  $t$ . Further,  $W(y_1, y_2)(t)$  is either zero for all  $t$  in  $I$  (if  $c = 0$ ) or else is never zero in  $I$  (if  $c \neq 0$ ).