

### Initial Conditions

Applying the initial condition yields the following:

$$\begin{aligned}
 f(r, \theta) &= \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) A_{mn} (\cos(m\theta)\bar{A}_{mn} + \sin(m\theta)\bar{B}_{mn}) \\
 &= \sum_{n=1}^{\infty} J_0(r\lambda_{0n}) A_{0n} \bar{A}_{0n} \\
 &+ \sum_{m=1}^{\infty} \left[ \left( \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) A_{mn} \bar{A}_{mn} \right) \cos(m\theta) + \left( \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) A_{mn} \bar{B}_{mn} \right) \sin(m\theta) \right]
 \end{aligned} \tag{1}$$

So, if  $r$  is held fixed, this is a Fourier series expansion of  $f(r, \theta)$ . That means we know, using the expressions for the Fourier coefficients of a function with period  $2\pi$ , that

$$\begin{aligned}
 a_0(r) &= \frac{1}{2\pi} \int_0^a f(r, \theta) d\theta = \sum_{n=1}^{\infty} J_0(r\lambda_{0n}) A_{0n} \bar{A}_{0n} \\
 a_m(r) &= \frac{1}{\pi} \int_0^a f(r, \theta) \cos(m\theta) d\theta = \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) A_{mn} \bar{A}_{mn} \\
 b_m(r) &= \frac{1}{\pi} \int_0^a f(r, \theta) \sin(m\theta) d\theta = \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) A_{mn} \bar{B}_{mn}
 \end{aligned}$$

The following calculation, which employs the orthogonality relations for Bessel functions, shows how we can calculate  $A_{0k}\bar{A}_{0k}$ :

$$\begin{aligned}
 \left[ a_0(r) \right. &= \left. \sum_{n=1}^{\infty} J_0(r\lambda_{0n}) A_{0n} \bar{A}_{0n} \right] J_0(r\lambda_{0k}) r \\
 \int_0^a a_0(r) J_0(r\lambda_{0k}) r dr &= \sum_{n=1}^{\infty} A_{0n} \bar{A}_{0n} \int_0^a J_0(r\lambda_{0n}) J_0(r\lambda_{0k}) r dr \\
 &= \sum_{n=1}^{\infty} A_{0n} \bar{A}_{0n} \left( \frac{a^2}{2} J_1^2(\alpha_{0k}) \delta_{kn} \right) \\
 &= A_{0k} \bar{A}_{0k} \left( \frac{a^2}{2} J_1^2(\alpha_{0k}) \right) \\
 A_{0k} \bar{A}_{0k} &= \frac{2}{a^2 J_1^2(\alpha_{0k})} \int_0^a a_0(r) J_0(r\lambda_{0k}) r dr
 \end{aligned}$$

where  $a_0(r) = \frac{1}{2\pi} \int_0^{2\pi} f(r, \theta) d\theta$ . If we like, we can combine these to finally get

$$A_{0k} \bar{A}_{0k} = \frac{1}{\pi a^2 J_1^2(\alpha_{0k})} \int_0^a \int_0^{2\pi} f(r, \theta) J_0(r\lambda_{0k}) r d\theta dr$$

Similar calculations yield the following results:

$$A_{mk}\bar{A}_{mk} = \frac{2}{\pi a^2 J_{m+1}^2(\alpha_{mk})} \int_0^a \int_0^{2\pi} f(r, \theta) \cos(m\theta) J_m(r\lambda_{mk}) r \, d\theta dr$$

$$A_{mk}\bar{B}_{mk} = \frac{2}{\pi a^2 J_{m+1}^2(\alpha_{mk})} \int_0^a \int_0^{2\pi} f(r, \theta) \sin(m\theta) J_m(r\lambda_{mk}) r \, d\theta dr$$

Therefore, we have determined that

$$A_{0n}\bar{A}_{0n} = \frac{1}{\pi a^2 J_1^2(\alpha_{0n})} \int_0^a \int_0^{2\pi} f(r, \theta) J_0(r\lambda_{0n}) r \, d\theta dr \quad (2)$$

$$A_{mn}\bar{A}_{mn} = \frac{2}{\pi a^2 J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} f(r, \theta) \cos(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr \quad (3)$$

$$A_{mn}\bar{B}_{mn} = \frac{2}{\pi a^2 J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} f(r, \theta) \sin(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr \quad (4)$$

Applying the other initial condition yields the following:

$$\begin{aligned} g(r, \theta) &= \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} c\lambda_{mn} J_m(r\lambda_{mn}) B_{mn} (\cos(m\theta)\bar{A}_{mn} + \sin(m\theta)\bar{B}_{mn}) \\ &= \sum_{n=1}^{\infty} J_0(r\lambda_{0n}) c\lambda_{0n} B_{0n} \bar{A}_{0n} \\ &\quad + \sum_{m=1}^{\infty} \left[ \left( \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) c\lambda_{mn} B_{mn} \bar{A}_{mn} \right) \cos(m\theta) + \left( \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) c\lambda_{mn} B_{mn} \bar{B}_{mn} \right) \sin(m\theta) \right] \end{aligned}$$

Notice that the only difference from what we just looked at in Eq. (1) is that  $A_{mn} \rightarrow c\lambda_{mn} B_{mn}$ , and  $f \rightarrow g$ . So we can make these substitutions in Eqs. (2)–(4), and we arrive at:

$$B_{0n}\bar{A}_{0n} = \frac{1}{c\lambda_{0n}\pi a^2 J_1^2(\alpha_{0n})} \int_0^a \int_0^{2\pi} g(r, \theta) J_0(r\lambda_{0n}) r \, d\theta dr$$

$$B_{mn}\bar{A}_{mn} = \frac{2}{c\lambda_{mn}\pi a^2 J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} g(r, \theta) \cos(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr$$

$$B_{mn}\bar{B}_{mn} = \frac{2}{c\lambda_{mn}\pi a^2 J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} g(r, \theta) \sin(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr$$

Our solution to the vibrating drumhead can therefore be written as the following:

$$\begin{aligned} u(r, \theta, t) &= \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) (A_{mn} \cos(c\lambda_{mn}t) + B_{mn} \sin(c\lambda_{mn}t)) (\bar{A}_{mn} \cos(m\theta) + \bar{B}_{mn} \sin(m\theta)) \\ &= \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) (A_{mn} \bar{A}_{mn} \cos(m\theta) + A_{mn} \bar{B}_{mn} \sin(m\theta)) \cos(c\lambda_{mn}t) \end{aligned}$$

$$\begin{aligned}
& + \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) (B_{mn} \bar{A}_{mn} \cos(m\theta) + B_{mn} \bar{B}_{mn} \sin(m\theta)) \sin(c\lambda_{mn}t) \\
u(r, \theta, t) & = \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) (a_{mn} \cos(m\theta) + b_{mn} \sin(m\theta)) \cos(c\lambda_{mn}t) \\
& + \sum_{m=0}^{\infty} \sum_{n=1}^{\infty} J_m(r\lambda_{mn}) (a_{mn}^* \cos(m\theta) + b_{mn}^* \sin(m\theta)) \sin(c\lambda_{mn}t)
\end{aligned}$$

where we have redefined the constants, and using  $\alpha_{mn} = a\lambda_{mn}$ , we get

$$\begin{aligned}
a_{0n} & = \frac{1}{\pi a^2 J_1^2(\alpha_{0n})} \int_0^a \int_0^{2\pi} f(r, \theta) J_0(r\lambda_{0n}) r \, d\theta dr \\
a_{mn} & = \frac{2}{\pi a^2 J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} f(r, \theta) \cos(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr \\
b_{mn} & = \frac{2}{\pi a^2 J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} f(r, \theta) \sin(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr \\
a_{0n}^* & = \frac{1}{c\alpha_{0n} \pi a J_1^2(\alpha_{0n})} \int_0^a \int_0^{2\pi} g(r, \theta) J_0(r\lambda_{0n}) r \, d\theta dr \\
a_{mn}^* & = \frac{2}{c\alpha_{mn} \pi a J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} g(r, \theta) \cos(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr \\
b_{mn}^* & = \frac{2}{c\alpha_{mn} \pi a J_{m+1}^2(\alpha_{mn})} \int_0^a \int_0^{2\pi} g(r, \theta) \sin(m\theta) J_m(r\lambda_{mn}) r \, d\theta dr
\end{aligned}$$